

(37)

$$y_p = A \cos 2t + B \sin 2t$$

$$y_p' = -2A \sin 2t + 2B \cos 2t$$

$$y_p'' = -4A \cos 2t - 4B \sin 2t$$

$$y_p'' + 2y_p' + 2y_p = \cos 2t(-4A + 2B + 2A) + \sin 2t(-4B - 4A + 2B) \\ = (-2A + 4B) \cos 2t + (-2B - 4A) \sin 2t$$

$$-2A + 4B = 10$$

$$-2B - 4A = 0 \quad -2A = B$$

$$5B = 10$$

$$B = 2$$

$$-2A = 2, \quad A = -1.$$

Steady state: $y_s = -\cos 2t + 2 \sin 2t$

method $y_p(t) = \frac{F_0}{\sqrt{(k-m\gamma)^2 + b^2\gamma^2}} \sin(\gamma t + \theta)$

$$m=1, \gamma=2, k=2, b=2, F_0=10$$

$$(k-m\gamma)^2 + b^2\gamma^2 = (2-2)^2 + 2^2 \cdot 2^2 = 2^2 + 2^2 \cdot 2^2 = 20$$

$$\sqrt{(\quad)^2 + b^2\gamma^2} = \sqrt{20} = 2\sqrt{5} = 4 + 16 = 20$$

$$\tan \theta = \frac{k-m\gamma^2}{b\gamma} = \frac{-2}{4} = -\frac{1}{2}$$

θ corresponds to pt in the 4th quadrant (+, -)

$$\theta = \tan^{-1}(-1/2) = -\tan^{-1}(1/2) \approx -0.464.$$

Steady state

$$y_p = \frac{10}{2\sqrt{5}} \sin(2t + \theta) = \sqrt{5} \sin(2t - \tan^{-1}(1/2))$$

$$\approx (2.236) \sin(2t - 0.464).$$